# Applied algebraic geometry: tensor decomposition

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#### **Observation**

K a field. Then  $A \in K^{m \times n}$  has  $\operatorname{rk} A \leq k \Leftrightarrow A$  can be written as  $\sum_{i=1}^k u_i v_i^T$  with  $u_i \in K^m, v_i \in K^n$ .

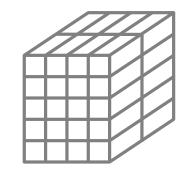
 $\Leftarrow$  each  $u_i v_i^T$  has rank 1 and  $\operatorname{rk}(B + C) \leq \operatorname{rk}(B) + \operatorname{rk}(C)$ ⇒ induction on k: if  $A \neq 0$ , take nonzero  $u \in \operatorname{colspace}(A)$ , w such that Aw = u, and v such that  $\ker A \subseteq \ker v^T$  and  $v^T w \neq 0$ . Then  $A' := A - \frac{uv^T}{v^T w}$  has  $\ker A' \supseteq Kw + \ker A$  so  $\operatorname{rk}A' < \operatorname{rk}A$ .

## Many variations

- matrices with structure (symmetric, skew)
- want the  $u_i$  pairwise  $\perp$ , and also the  $v_i$  (SVD over  $\mathbb{R}$  or  $\mathbb{C}$ )
- approximations by low-rank matrices (SVD)

**Central question:** How does this all generalise to tensors?

**Answer 1:** a multidimensional array of numbers.  $(a_{ijk})_{i \in [5], j \in [4], k \in [2]}$ 



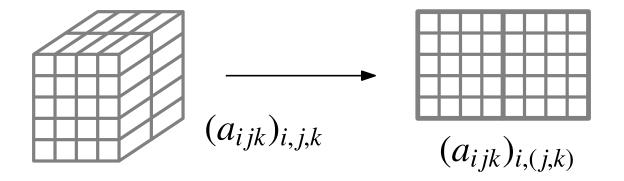
**Answer 2:** an element of  $T := V_1 \otimes \cdots \otimes V_d$  for  $V_1, \ldots, V_d$  f.d. vector spaces over K

#### Recall

Elements of T are formal linear combinations of symbols  $v_1 \otimes \cdots \otimes v_d$  modulo the space spanned by elements of the form  $v_1 \otimes \cdots \otimes (v_i + u_i) \otimes \cdots \otimes v_d - v_1 \otimes \cdots \otimes v_i \otimes \cdots \otimes v_d - v_1 \otimes \cdots \otimes u_i \otimes \cdots \otimes v_d$  and  $v_1 \otimes \cdots \otimes (cv_i) \otimes \cdots \otimes v_d - c(v_1 \otimes \cdots \otimes v_d)$ 

- {linear  $f: T \to W$ }  $\cong$  {multilin  $f: V_1 \times \cdots \times V_d \to W$ }
- $B_i$  basis of  $V_i \Rightarrow B_1 \otimes \cdots \otimes B_d$  basis of T (relates answers 1,2)
- $V_1^* \otimes \cdots \otimes V_d^* \cong T^*, (x_1 \otimes \cdots \otimes x_d)(v_1 \otimes \cdots \otimes v_d) = \prod_i x_i(v_i)$

Given a partition  $[d] = I \cup J$ , have a natural map  $b_{I,J} : T \to T_I \otimes T_J$  with  $T_I := \bigotimes_{i \in I} V_i$ , given by  $v_1 \otimes \cdots \otimes v_p \mapsto (\bigotimes_{i \in I} v_i) \otimes (\bigotimes_{i \in J} v_j)$ . Here we forget the tensor product structure on  $T_I$ ,  $T_J$ . Similarly with more factors.



In general,  $U^* \otimes V \cong \operatorname{Hom}_K(U, V)$ ,  $x \otimes v \mapsto (u \mapsto x(u)v)$ .

Take  $t \in T$ . For each  $i \in [d]$ , let  $U_i := \text{image of } t$  as linear map  $T_{[d]-i}^* \to V_i$ . Then  $t \in \bigotimes_i U_i$  and the  $U_i$  are minimal with this property. All dim  $U_i = 1 \Leftrightarrow t = u_1 \otimes \cdots \otimes u_d$ , some nonzero  $u_i$ .

**Definition** t is called pure if  $t = u_1 \otimes \cdots \otimes u_d$  for some  $u_i$ .

## **Proposition**

Pure tensors in T form a Zariski-closed subset X defined by quadratic polynomials.

### **Proof**

For d=2 these are the rank  $\leq 1$  matrices, defined by  $2\times 2$ -subdeterminants. For d>1, t pure iff  $b_{\lceil d\rceil-i,i}t$  pure for all i.

**Remark**  $|K| = \infty \rightsquigarrow 2 \times 2$ -dets of flattenings generate ideal(X).

#### **Definition**

T any vector space,  $X \subseteq V$  Zariski-closed cone spanning T. Then

- $\bullet kX := \{x_1 + \cdots + x_k \mid x_i \in X\};$
- $\operatorname{rk}_X t := \min\{k \mid v \in kX\} \text{ the } X\text{-}rank \text{ of } v;$
- kX is the k-th secant variety of X; and
- $\operatorname{brk}_X t := \min\{k \mid v \in kX\}$  the *X-border rank* of *v*.

For  $X \subseteq T$  above, this is *tensor* (border) rank.

 $t \in K^2 \otimes K^2 \otimes K^2$ , write  $t = e_1 \otimes A + e_2 \otimes B$  with  $A, B \times 2$ -matrices

- suppose  $\operatorname{rkb}_{1,23}t = 2$ , i.e., A, B linearly independent
- then  $\operatorname{rk} t = 2$  iff  $\exists C, D$  of rank 1 and u, v such that  $t = u \otimes C + v \otimes D$
- iff  $\langle A, B \rangle$  contains two linearly independent rank-1 matrices
- iff the discriminant  $\Delta(t)$  of the quadratic polynomial  $\det(xA + yB)$  is a nonzero square—this is *Cayley's hyperdeterminant*:

$$\Delta(t) = a_{2,2}^2 b_{1,1}^2 - 2a_{2,1} a_{2,2} b_{1,1} b_{1,2} + a_{2,1}^2 b_{1,2}^2 - 2a_{1,2} a_{2,2} b_{1,1} b_{2,1} - 2a_{1,2} a_{2,1} b_{1}, 2b_{2,1} + 4a_{1,1} a_{2,2} b_{1,2} b_{2,1} + a_{1,2}^2 b_{2,1}^2 + 4a_{1,2} a_{2,1} b_{1,1} b_{2,2} - 2a_{1,1} a_{2,2} b_{1,1} b_{2,2} - 2a_{1,1} a_{2,1} b_{1,2} b_{2,2} - 2a_{1,1} a_{1,2} b_{2,1} b_{2,2} + a_{1,1}^2 b_{2,2}^2$$

Picture for K alg closed: For  $K = \mathbb{R}$  have  $\Delta > 0 \rightsquigarrow \text{rank } 2$ ,

 $\Delta < 0 \rightsquigarrow \text{rank } 3.$ 

pure 
$$\Delta = 0$$
, not pure  $\rightsquigarrow$  rank 3  
 $\Delta \neq 0 \rightsquigarrow$  rank 2