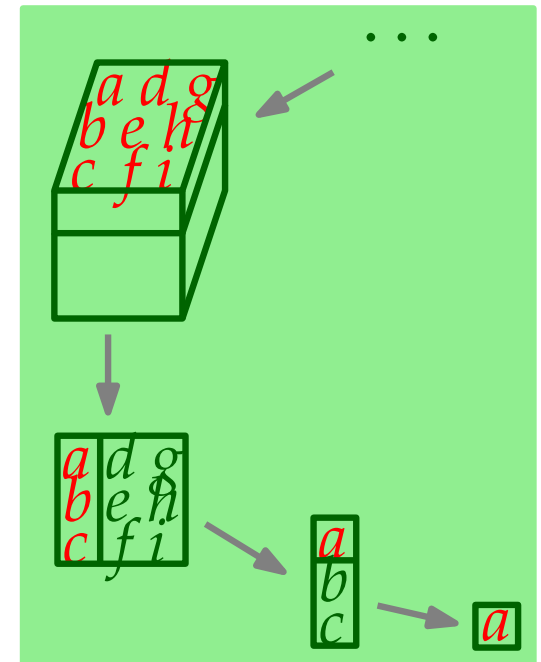


Symmetries and ∞ -dim limits of algebro-statistical models

a_{11}	a_{12}	a_{13}	\cdots
a_{21}			
a_{31}			
\vdots			



Part I: some infinite-dimensional commutative algebra

What is an infinite-dimensional variety?

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*inductive limits of finite-dimensional varieties,
projective limits, spectra of infinite-dimensional rings, etc.*

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V^* : dual space, topological space with Zariski topology

Closed subsets $X \subseteq V^*$ are called *infinite-dimensional varieties*.

Example

$V = \langle x_{ij} \mid i, j \in \mathbb{N} \rangle$, $X \subseteq V^*$ defined by equations $x_{ij}x_{kl} - x_{il}x_{kj}$

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Sequence model

If $V_1 \subseteq V_2 \subseteq \dots$ finite-dimensional with $V = \bigcup_i V_i$, then

$V^* = \lim_{\leftarrow} V_i^*$ with $V_1^* \longleftarrow V_2^* \longleftarrow \dots$

(both as set and as topological space)

Noetherianity modulo group actions

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Assume a group G acts by linear transformations on V
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(Non-)Examples of G-Noetherianity

5

Finite-by-infinite matrices

Fix $k \in \mathbb{N}$;

$\text{Sym}(\mathbb{N})$ acts on $V = \langle x_{ij} \mid i \in [k], j \in \mathbb{N} \rangle$

by $\pi(x_{ij}) = x_{i\pi(j)}$.

$$\begin{array}{ccc} x_{11} & x_{12} & \cdots \\ \vdots & & \\ x_{k1} & x_{k2} & \cdots \end{array}$$

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[Cohen 87, Hillar-Sullivant 09]

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$\text{Sym}(\mathbb{N})$ acts by $\pi(x_{ij}) = x_{\pi(i),\pi(j)}$

$\rightsquigarrow \mathbb{C}[x_{ij} \mid i, j \in \mathbb{N}]$ is *not* $\text{Sym}(\mathbb{N})$ -Noetherian;

e.g. the $\text{Sym}(\mathbb{N})$ -stable ideal generated by

$x_{12}x_{21}, x_{12}x_{23}x_{31}, x_{12}x_{23}x_{34}x_{41}, \dots$

is not $\text{Sym}(\mathbb{N})$ -finitely generated.

$$\begin{matrix} x_{11} & x_{12} & \cdots \\ x_{21} & & \\ \vdots & & \end{matrix}$$

(neither $\text{Sym}(\mathbb{N}) \times \text{Sym}(\mathbb{N})$ -Noetherian)

Theorem (*Matrices of bounded rank*)

$\mathbb{C}[x_{ij} \mid i, j \in \mathbb{N}] / (\text{all } (k+1) \times (k+1)\text{-subdeterminants})$
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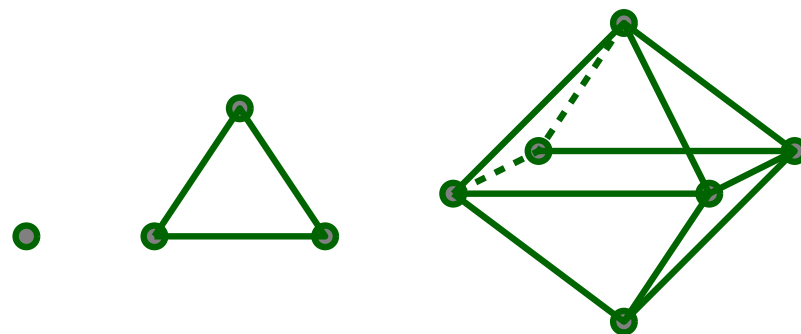
[D-Eggermont 2014]

$(\mathbb{C}^{\mathbb{N} \times \mathbb{N}})^p$ is $\text{GL}_{\mathbb{N}} \times \text{GL}_{\mathbb{N}}$ -Noetherian for each p , via

$(g, h) \circ (x, \dots, z) := (gxh^{-1}, \dots, gzh^{-1}).$

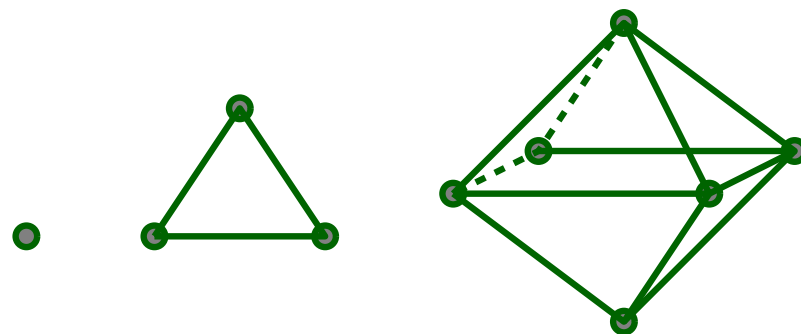
Example: second hypersimplex

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Markov basis M_n

[De Loera-Sturmfels-Thomas 1995]

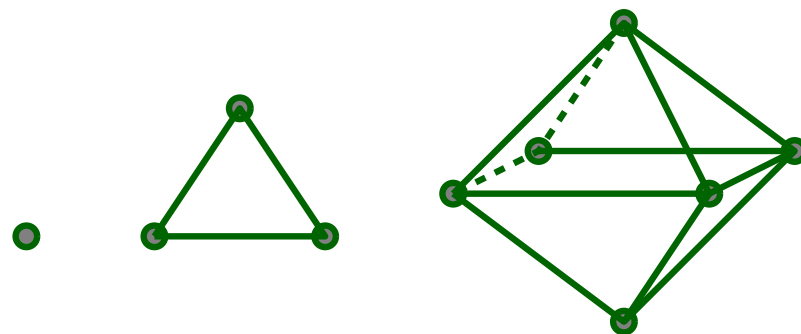
$v_{ij} = v_{ji}$ and $v_{ij} + v_{kl} = v_{il} + v_{kj}$ for i, j, k, l distinct

\leadsto if $\sum_{ij} c_{ij} v_{ij} = \sum_{ij} d_{ij} v_{ij}$ with $c_{ij}, d_{ij} \in \mathbb{Z}_{\geq 0}$,

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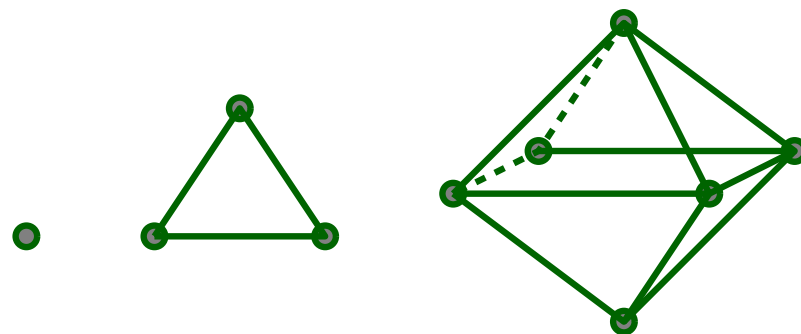
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[D-Eggermont-Krone-Leykin 2013]

For *any* family $(P_n \subseteq \mathbb{Z}^F \times \mathbb{Z}^{k \times n})$, F finite, if $P_n = \text{Sym}(n)P_{n_0}$ for $n \geq n_0$, then $\exists n_1$: for $n \geq n_1$ has a Markov basis M_n with $M_n = \text{Sym}(n)M_{n_0}$.

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Explicit results for width $n_0 = 2$:

[Kahle-Krone-Leykin 2014]

Part II: Applications to algebraic-statistical models

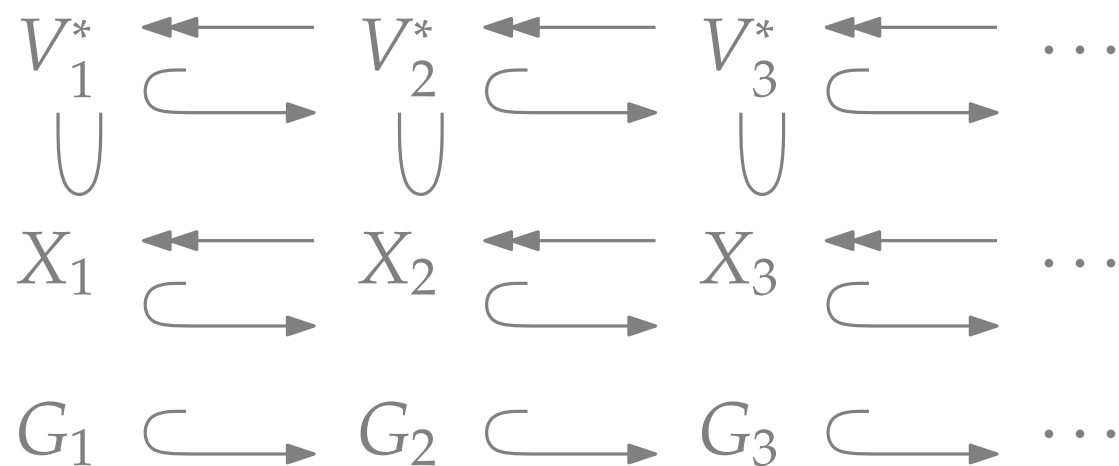
Setting

V_1^*, V_2^*, \dots fin-dim spaces; $X_i \subseteq V_i^*$ subvariety
 G_i group acting linearly on V_i^* preserving X_i
 $G_i \subseteq G_{i+1}$ & maps $\pi : V_{i+1}^* \rightarrow V_i^*$ and $\iota : V_i^* \rightarrow V_{i+1}^*$ both
 G_i -equivariant, mapping X_{i+1} into X_i and v.v. & $\pi \circ \iota = \text{id}$

$$\begin{array}{ccccccc}
 V_1^* & \xleftarrow{\quad} & V_2^* & \xleftarrow{\quad} & V_3^* & \xleftarrow{\quad} & \dots \\
 \cup & \hookrightarrow & \cup & \hookrightarrow & \cup & \hookrightarrow & \\
 X_1 & \xleftarrow{\quad} & X_2 & \xleftarrow{\quad} & X_3 & \xleftarrow{\quad} & \dots \\
 & \hookrightarrow & & \hookrightarrow & & \hookrightarrow & \\
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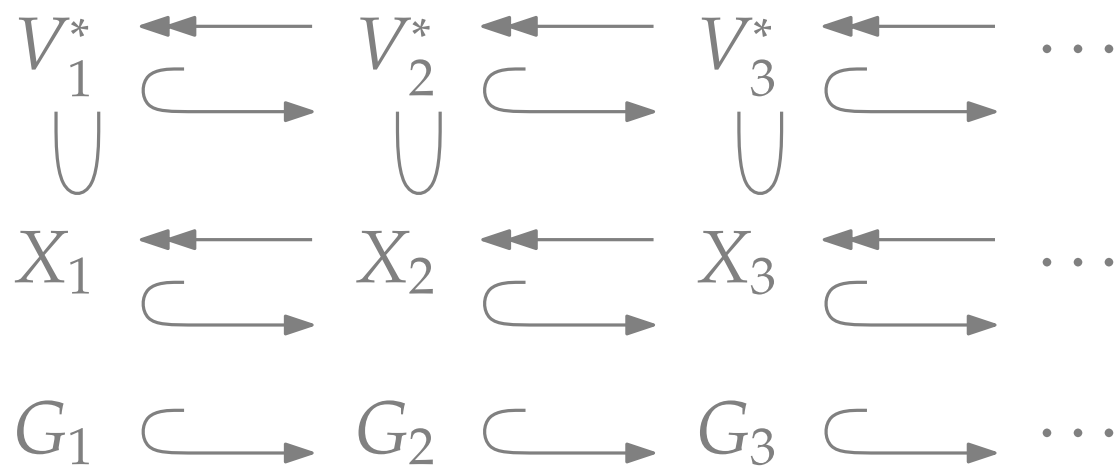


Definition

Sequence $(X_i \subseteq V_i^*)_i$
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$$\rightsquigarrow V_\infty^* := \lim_{\leftarrow} V_n; X_\infty := \lim_{\leftarrow} X_n; G_\infty := \cup_n G_n$$

Lemma Stabilisation is “equivalent” to: $X_\infty \subseteq V_\infty^*$ is defined
 by finitely many G_∞ -orbits of equations.

I: The independent set theorem

10

Fixed row and column sums

$A, B \in \mathbb{Z}_{\geq 0}^{m \times n}$ with $a_{i+} = b_{i+}$ and $a_{+j} = b_{+j}$
 $\Rightarrow \exists A = A_0, A_1, \dots, A_k = B \in \mathbb{Z}_{\geq 0}^{m \times n}$ with

$A_l - A_{l-1} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \rightsquigarrow$ moves “independent” of m, n .

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Theorem

[Diaconis-Sturmfels 1998]

basis of Markov moves = generating set of toric ideal
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Conjecture

[Hoşten-Sullivant 2007]

Similar stabilisation conjecture for Markov basis for
sampling higher-dimensional contingency tables.

Hierarchichal models

F family of subsets of $[m]$

$y(i_1, \dots, i_m)$ and $x(S, (i_s)_{s \in S})$ for $S \in F$ variables

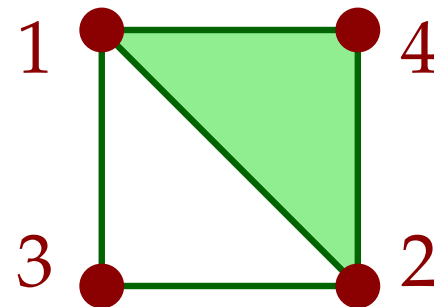
$I := \ker[y(i_1, \dots, i_m) \mapsto \prod_{A \in S} x(S, (i_s)_{s \in S})]$

Example

$m = 4, F = \{124, 13, 23\}$

variables $y(abcd), x(abd), z(ac), u(bc)$

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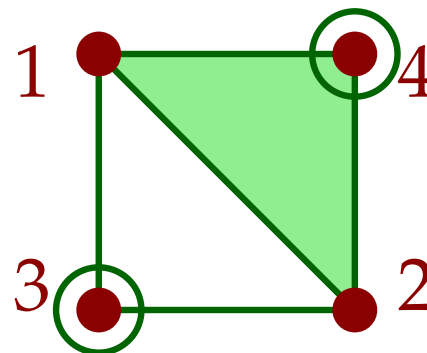
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Theorem

[Hillar-Sullivant 2012]

If $T \subseteq [m]$ independent set ($|T \cap S| \leq 1$ for $S \in F$);

$i_t, t \in T$ run through \mathbb{N} and $i_t, t \notin T$ through $[r_t]$

$\rightsquigarrow I$ generated by finitely many $\text{Inc}(\mathbb{N})$ -orbits

(now this also follows from D-Eggermont-Krone-Leykin)

II: Cloning sinks in a Gaussian Bayesian model 12

G : directed acyclic graph on $[n]$

$X_i, i \in [n]$: jointly Gaussian

$X_j = \sum_{i \in \text{pa}(j)} \lambda_{ij} X_i + a_j \epsilon_j$ where the $\epsilon_j \sim N(0, 1)$ independent

$$\rightsquigarrow \Sigma = (I - \Lambda)^{-T} \text{diag}(a_1^2, \dots, a_n^2) (I - \Lambda)^{-1}$$

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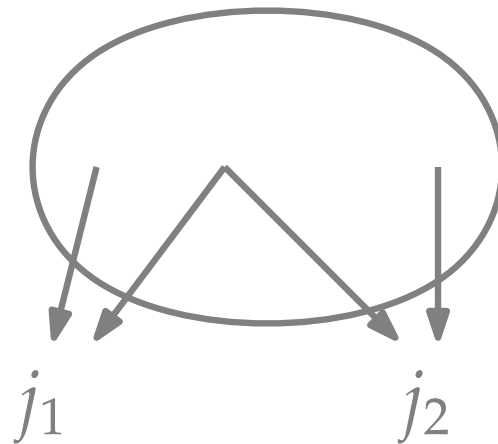
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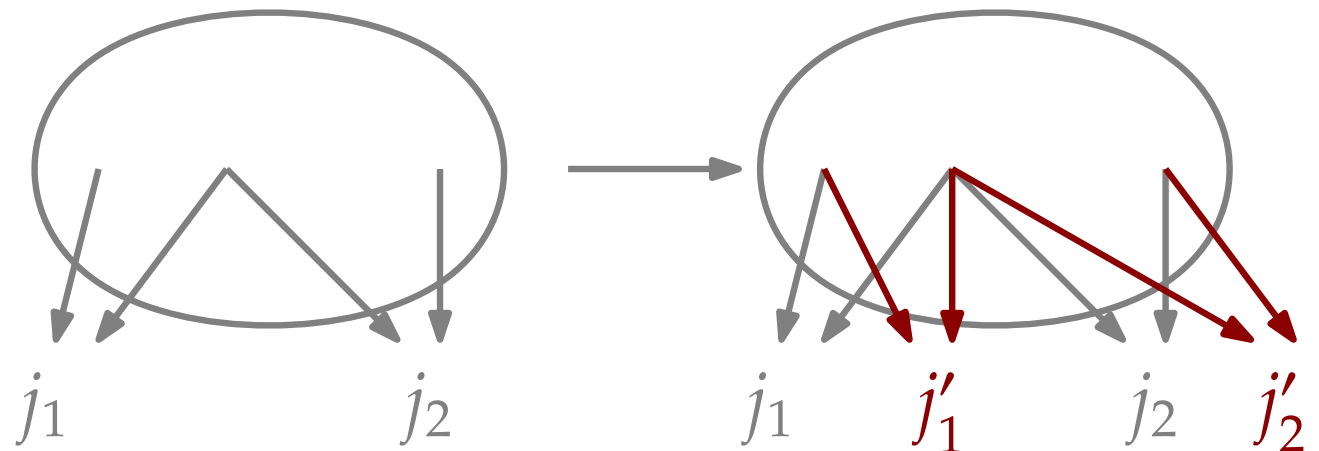
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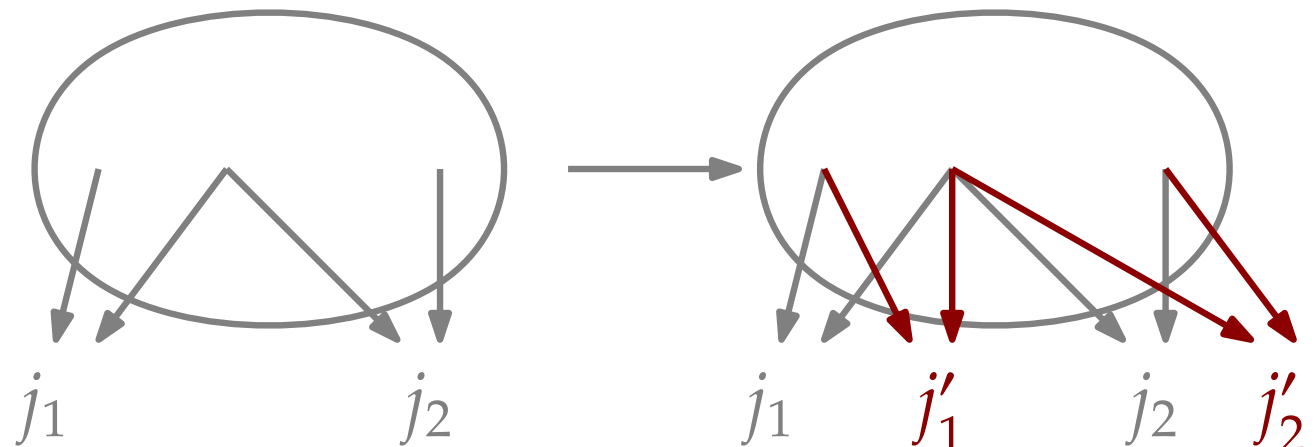
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Cloning sinks



Theorem

Model stabilises under cloning sinks (via permuting clones).

[“D 2010”]

Stabilisation for parameterised graphical models 13

undirected	DAG with hidden vars	
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$M(G) := \{(p_{i_1, \dots, i_n} = \prod_C \theta_{\mathbf{i}_C}^C)_{i_1, \dots, i_n}\} \subseteq \mathbb{C}^R$ prod over all cliques C $\theta^C \in \mathbb{C}^{R_C}$	$\{(p_{i_1, \dots, i_n} = \prod_{j \in [n]} \theta_{i_j (i_k)_{k \in \text{pa}(j)}}) \} \subseteq \mathbb{C}^R$ $\forall \mathbf{i} \in R_{\text{pa}(j)} : \sum_{i_j} \theta_{i_j \mathbf{i}} = 1$ hide variables in H	<i>discrete</i> $R = \prod_j [r_j]$
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$M(G) := \{\Sigma = K^{-1}\}$ $K_{ij} = 0$ if $ij \notin E(G)$ $M(G) \subseteq \mathbb{C}^{n \times n}$	$\{\Sigma = (I - \Lambda)^{-T} D (I - \Lambda)^{-1}\}$ $\Lambda_{ij} = 0$ if $i \nrightarrow j$ $M(G) \subseteq \mathbb{C}^{([n]-H) \times ([n]-H)}$	<i>Gaussian</i> <i>mean 0</i>
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IV: Nonnegative matrix rank

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Definition

$$C \in \mathbb{R}_{\geq 0}^{m \times n} \rightsquigarrow \text{rk}_{\geq 0} C := \min\{r \mid \exists (A, B) \in \mathbb{R}_{\geq 0}^{m \times r} \times \mathbb{R}_{\geq 0}^{r \times n} : C = AB\}$$

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Observation/Theorem

[Kubjas, Robeva, Sturmfels 2013]

EM-algorithm for $M_r^{m \times n}$ often converges to boundary!

Explicit, quantifier-free expression for $r = 2$.

Algebraic boundary

$\overline{\partial M_r^{m \times n}}$: Zariski closure $\subseteq \mathbb{C}^{m \times n}$

hypersurface in the variety of rank- r matrices

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Theorem

[Kubjas-Robeva-Sturmfels 2013]

Apart from coordinate hyperplanes, for $m, n \geq 4$, $\overline{\partial M_3^{m \times n}}$ has $2 \operatorname{Sym}(m) \times \operatorname{Sym}(n)$ -orbits of irreducible components, parameterised by the following and its transpose:

$$\begin{bmatrix} 0 & * & * \\ * & 0 & * \\ * & * & 0 \\ * & * & * \end{bmatrix} \quad \begin{bmatrix} 0 & 0 & * & * & * \\ * & * & 0 & * & * \\ * & * & * & 0 & * \end{bmatrix}$$

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Conjecture

This component has a GB of 4×4 minors plus $\binom{m}{3}$ sextics.

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*Now a **Theorem** due to Eggermont-Horobeŭ-Kubjas.
But what about higher nonnegative rank??*

- Many algebro-statistical models fit into families with a meaningful limit.
- There is an ever growing body of commutative algebra for dealing with these limits up to symmetry.
- Do discrete Bayesian models stabilise under cloning sinks?
- Do undirected Gaussian graphical models exhibit any kind of stabilisation?
- If you have other families of models where you expect stabilisation, come talk to me!

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Děkuji!