

# Classical theory of Lie algebras

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DIAMANT Intercity Seminar Eindhoven  
27 October 2006

# Lie algebra

vector space  $L$  with  
bilinear *bracket*

$$[\cdot, \cdot] : L \times L \rightarrow L$$

subject to *anti-commutativity*

$$[x, x] = 0 \quad (\leadsto [x, y] = -[y, x])$$

and *Jacobi identity*

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$

# First construction: linear maps

$L := \{\text{linear maps on a vector space } V\} =: \text{End}(V)$

$[A, B] := AB - BA$  *commutator*

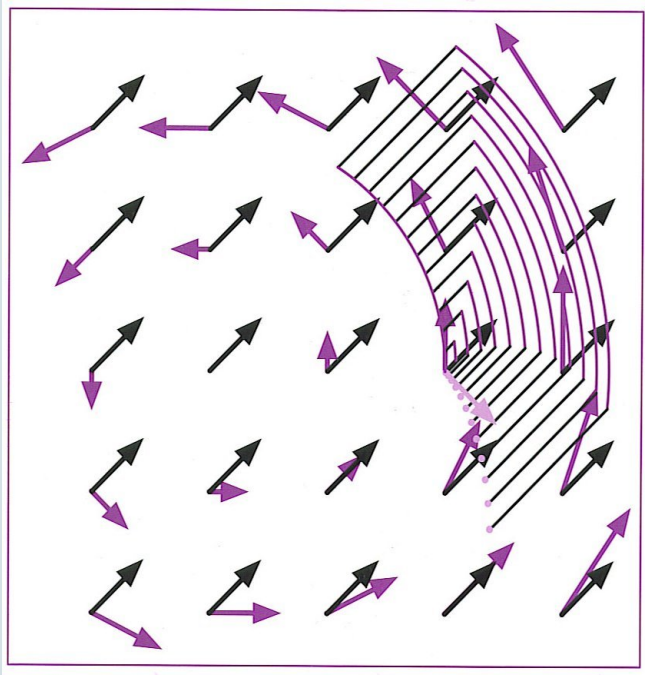
anti-commutativity

$$[A, A] = AA - AA = 0$$

Jacobi identity

$$\begin{aligned} & [A, [B, C]] + [B, [C, A]] + [C, [A, B]] \\ &= ABC - \textcolor{red}{ACB} - \textcolor{green}{BCA} + \textcolor{blue}{CBA} \\ &+ \textcolor{green}{BCA} - \textcolor{blue}{CBA} - \textcolor{yellow}{CAB} + \textcolor{orange}{BAC} \\ &+ \textcolor{yellow}{CAB} - \textcolor{orange}{BAC} - ABC + \textcolor{red}{ACB} \\ &= 0 \end{aligned}$$

## Second construction: vector fields



$X, Y$  vector fields on  $\mathbb{R}^n$   
 $\rightsquigarrow$  so is  $[X, Y]$

operation (derivation) on functions

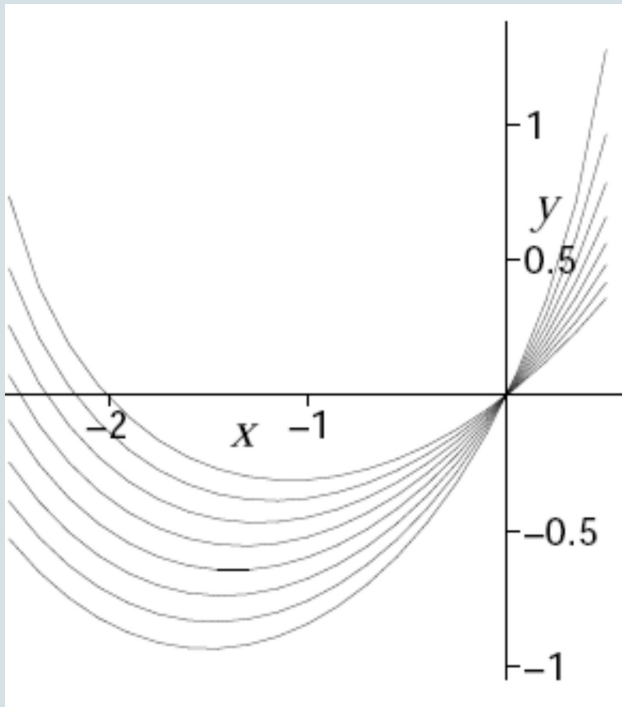
$$X(f)(p) = (df)(X(p))$$

bracket  $\rightsquigarrow$  commutator

$$[x\partial_y - y\partial_x, \partial_x + \partial_y] = \partial_x - \partial_y$$

Jacobi identity follows!

# Vector fields as infinitesimal symmetries



ODE

$$y^{(4)} - \frac{5(y^{(3)})^2}{3y^{(2)}} - (y^{(2)})^{5/3} = 0$$

infinitesimal rotational symmetry

$$x\partial_y - y\partial_x$$

Sophus Lie ( $\sim 1890$ ): ODE  
 $\rightsquigarrow$  algebra of vector fields in  $\mathbb{R}^2$   
classified up to diffeomorphisms  
analogy with Galois theory?

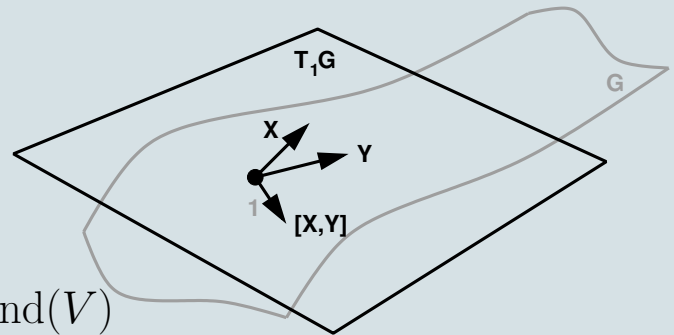
$\rightsquigarrow$  helps solving (computer algebra)

# Third construction: Lie algebras from groups

$V$  finite-dimensional vector space

$GL(V) := \{\text{invertible } g \in \text{End}(V)\}$

$G$  closed subgroup of  $GL(V)$



$T_I G =$  tangent space at  $I \in G \subseteq \text{End}(V)$

**fact:** closed under commutator

$\rightsquigarrow \mathfrak{g} := (T_I(G), [\cdot, \cdot])$  Lie algebra of  $G$

properties of  $G \rightsquigarrow$  properties of  $\mathfrak{g}$

e.g.  $G$  Abelian  $\Rightarrow [\mathfrak{g}, \mathfrak{g}] = 0$

# Lie algebras from classical groups

## B/D

non-degenerate symmetric bilinear form on  $V$

$$G := \{g \mid g^T g = I\} =: O(V)$$

$$\rightsquigarrow \mathfrak{g} = \{X \mid (I + \epsilon X)^T (I + \epsilon X) = I \mod \epsilon^2\} = \{X \mid X^T + X = 0\}$$

$$\rightsquigarrow \mathfrak{o}(V) = \mathfrak{so}(V)$$

$$\text{note } (XY - YX)^T = Y^T X^T - X^T Y^T = -(XY - YX)$$

## A

$$SL(V) := \{\text{determinant } 1\} \rightsquigarrow \mathfrak{sl}(V) := \{\text{trace } 0\}$$

## C

$Sp(V)$ ,  $\mathfrak{sp}(V)$  like  $O(V)$ ,  $\mathfrak{o}(V)$  but skew form

## Intermezzo: exponential map

Lie algebra elements are “infinitesimal group elements”

often  $x \in L \rightsquigarrow \exp(tx) = 1 + tx + \frac{t^2}{2!}x^2 + \dots$  “real group element”

1-parameter group:  $\exp((s+t)x) = \exp(sx)\exp(tx)$

characteristic zero needed?

### examples

$L = \mathfrak{g} \subseteq \mathfrak{gl}(\mathbb{C}^n) \rightsquigarrow \exp(tx) = e^{tx}$

$L$  of vector fields  $\rightsquigarrow \exp(tx)$  is the flow

### open problem

$V = p(x, y, z)\partial_x + q(x, y, z)\partial_y + r(x, y, z)\partial_z$

$p, q, r$  polynomials  $\in \mathbb{Q}[x, y, z]$

decide algorithmically:

$$\exp(tV)x = x + tp + \frac{t^2}{2!}Vp + \dots \text{ polynomial in } t?$$



# Theory

**goal (this talk): classification**

finite-dimensional simple Lie algebras

certain Lie algebras of vector fields

**tool: representation theory**

$L \rightarrow \text{End}(V)?$

$L \rightarrow \{\text{vector fields}\}?$

**tool: structure theory**

ideals

subalgebras

simple Lie algebras

# Structure theory: ideals and simple Lie algebras

$I \subseteq L$  *ideal* if  $[I, L] \subseteq I$   
( $\leadsto$  normal subgroups)

$L$  *simple* if  $0$  and  $L$  are the only ideals  
(and  $L$  not 1-dimensional)

$\mathfrak{sl}(V)$ ,  $\mathfrak{so}(V)$ ,  $\mathfrak{sp}(V)$  are (usually) simple

other finite-dimensional ones?

# Representation theory: adjoint representation

Jacobi identity

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$

$\Leftrightarrow$

$$[[y, z], x] = [y, [z, x]] - [z, [y, x]]$$

$\Leftrightarrow \text{ad} : L \rightarrow \text{End}(L), y \mapsto [y, \cdot]$  intertwines bracket and commutator

$$\text{ad}([y, z]) = [\text{ad}(y), \text{ad}(z)]$$

$\text{ad}$  is the *adjoint representation* of  $L$

(with kernel  $\{x \in L \mid [x, L] = 0\}$ , the *center*)

fundamental tool in structure theory and classification!

# Structure theory: Cartan subalgebras

$L$  simple finite-dimensional over  $\mathbb{C}$

*Cartan subalgebra*  $H$ : maximal with  $H$  Abelian and all  $\text{ad}_L(h)$  diagonalisable  
 $\leadsto \text{ad}_L(H)$  simultaneously diagonalisable

$H$  unique up to (inner) automorphisms of  $L$

$$L = \mathfrak{sl}_3 = \mathfrak{sl}(\mathbb{C}^3)$$

$$H = \left\{ \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & -a-b \end{pmatrix} \right\} \text{ ad-diagonalisable, e.g.}$$

$$\left[ \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & -a-b \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right] = (a-b) \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

# Structure theory: root systems

$H$  Cartan subalgebra in  $L$

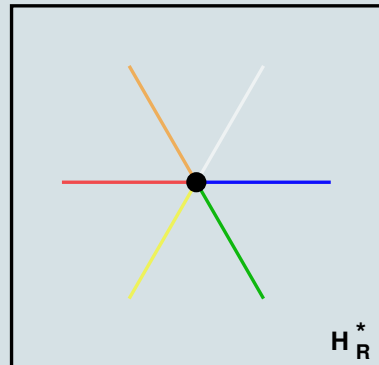
$\rightsquigarrow L$  direct sum of common eigenspaces  $L_\alpha$ ,  $\alpha \in H^*$

$\Phi(L) := \{\text{all such } \alpha\} \setminus \{0\}$  root system ( $L_0 = H$ )

$L = \mathfrak{sl}_3 \rightsquigarrow |\Phi| = 6$ :

$$\begin{pmatrix} * & * & * \\ * & * & * \\ * & * & * \end{pmatrix}$$

eigenspaces



root system  $\Phi$

**fact:** every root space  $L_\alpha$ ,  $\alpha \in \Phi$  1-dimensional

# Classification

*abstract* root system:

finite set in Euclidean space, with certain axioms

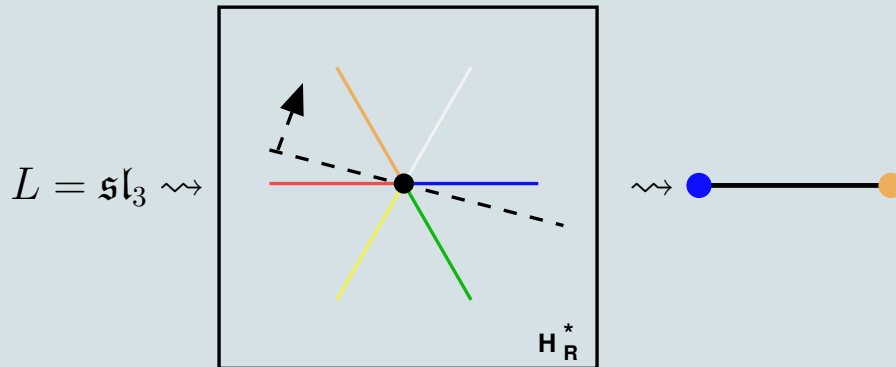
Cartan (1894):

$L \mapsto \Phi(L)$  is bijection

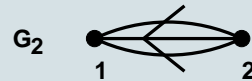
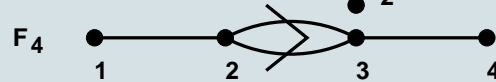
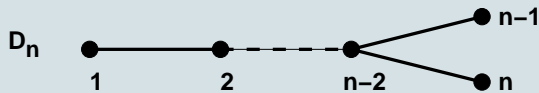
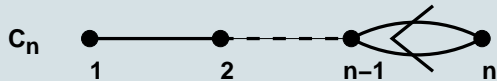
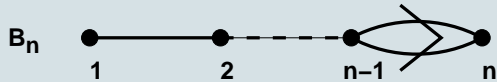
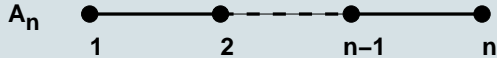
$\{ \text{finite-dimensional complex simple Lie algebras} \} \rightarrow \{ \text{root systems} \}$

root systems classified

root systems classified combinatorially through *Dynkin diagrams*:



# Classification: root systems



all are Lie algebras of groups

$$A_n \longleftrightarrow \mathfrak{sl}_{n+1}$$

$$B_n \longleftrightarrow \mathfrak{so}_{2n+1}$$

$$C_n \longleftrightarrow \mathfrak{sp}_{2n}$$

$$D_n \longleftrightarrow \mathfrak{so}_{2n}$$

# Representation theory: vector fields

$L \supseteq M$  Lie algebras

$m := \text{codim}_L M < \infty$

Guillemin/Sternberg/Blattner (1960s):

$L \rightarrow \{ \text{(formal) vector fields in } m \text{ variables} \}$   
s.t.  $M$  stabiliser of 0

$$L = \mathfrak{sl}_3 = \left\{ \begin{pmatrix} * & * & * \\ * & * & * \\ * & * & * \end{pmatrix} \right\}, M = \left\{ \begin{pmatrix} * & * & * \\ 0 & * & * \\ 0 & * & * \end{pmatrix} \right\}$$

$\rightsquigarrow \partial_1, \partial_2,$

$x_1 \partial_2, 2x_1 \partial_1 + x_2 \partial_2, -x_1 \partial_1 + x_2 \partial_2, x_2 \partial_1$

$-x_1^2 \partial_1 - x_1 x_2 \partial_2, -x_1 x_2 \partial_1 - x_2^2 \partial_2$

$(L, M)$  primitive if  $\nexists N : L \supsetneq N \supsetneq M$



# Classification: infinite-dimensional primitive Lie algebras

Cartan (Guillemin, Sternberg, . . .) classified  
*infinite-dimensional primitive pseudo-groups*:  
 $L$  complex infinite-dimensional,  $\text{codim}_L M = m < \infty$   
 $(L, M)$  primitive (+technical conditions)

$\leadsto$  six possibilities:

$L \cong W((m)) :=$  all formal vector fields

$L \cong (C)S((m)) :=$  those fixing a volume form (up to a constant)

$L \cong (C)H((2r)) :=$  those fixing a symplectic form (up to a constant)

$L \cong K((2r + 1)) :=$  those leaving a contact structure

e.g.  $S((m)) = \{X = \sum_{i=1}^m f_i \partial_i \mid \text{div } X := \sum_i \partial_i(f_i) = 0\}$

# Characteristic $p$ and divided powers

$$\operatorname{codim}_L M = m$$

over  $\mathbb{C}$ :

$$L \rightarrow \{\text{derivations of } \mathbb{C}[[x_1, \dots, x_m]]\}$$

characteristic  $p$ :

$$L \rightarrow \{\text{derivations of } \mathcal{O}((m))\}$$

$$\mathcal{O}((m)) := \left\{ \sum_{r \in \mathbb{N}^m} c_r x^{(r)} \right\} \quad x^{(r)} x^{(s)} := \frac{(r+s)!}{r!s!} x^{(r+s)}$$

(think of  $x^{(r)}$  as  $\frac{x^r}{r!}$ )

$\mathcal{O}((m))$  has nice finite-dimensional subalgebras

e.g.  $r_i < p, s_i < p, r_i + s_i \geq p \Rightarrow x^{(r)} x^{(s)} = 0$

$\rightsquigarrow$  finite-dimensional versions of  $W, (C)S, (C)H, K$  in char  $p$   
these are simple; are these + the classical ones all?

## Wrapping up

take away:

1. finite-dimensional simple Lie algebras  $/\mathbb{C}$  classified (combinatorially): 4 infinite series  $A_n, B_n, C_n, D_n$ , 5 exceptional Lie algebras  $E_6, E_7, E_8, F_4, G_2$
2. infinite-dimensional primitive Lie algebras of vector fields  $/\mathbb{C}$  classified; finite-dimensional analogues in char  $p$
3. Lie algebra elements are “infinitesimal group elements”; exponential map “integrates” them

many subjects not touched upon: geometry, physics, Lie super-algebras, algorithms . . .